

Argo floats

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Ships of opportunity

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Autonomous underwater vehicle

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Barrett, N, Seiler, J, Anderson, T, Williams, S, Nicol, S, Hill, N 2010, Using an autonomous underwater vehicle to inform management of biodiversity in shelf waters, Proceedings of Oceans 2010 IEEE, Sydney, Australia, May, 2010, Sydney

Jakuba, M, Pizarro, O, Williams, S 2010, High resolution, consistent navigation and 3D optical reconstructions from AUVs using magnetic compasses and pressure-based depth sensors, Proceedings of Oceans 2010 IEEE, Sydney, Australia, May, 2010, Sydney

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Bryson, M, Johnson-Robertson, M, Pizarro, O, Williams, S 2012, Colour-consistent structure-from-motion models using underwater imagery, Proceedings of the 2012 Robotics: science and systems conference, Sydney, Presenter: Mitchell Bryson

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Steinberg, D, Pizarro, O, Williams, S 2013, Synergistic clustering of image and segment descriptors for unsupervised scene understanding, Proceedings of Computer Vision (ICCV) 2013 IEEE International Conference, Sydney, Presenter: Daniel Steinberg

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National mooring network

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Pattiaratchi, C, et, al. 2015, Meteotsunamis in south-western Australia, Proceedings of Coasts and Ports 2015: 22nd Australasian Coastal and Ocean Engineering Conference and the 15th Australasian Port and Harbour Conference, Auckland, Presenter: Charitha Pattiaratchi

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Ocean radar

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Animal tracking

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